

Lecture 10: Synthetic Controls

March 25, 2020



### **Course Administration**

### Overview

Synthetic Control Set-up

Goal in Estimation

**Convex Hull Required** 

Estimation

### Examples

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- 1. Hope everyone is doing ok. Let me know if you are having difficulties.
- 2. Today
  - Synthetic control: end by 7 pm
  - Then you do the in-class workshop virtually
- 3. Going forward
  - Lectures 11, 12, 13: I am available during this time for paper advice.
    - Share your screen! I'll give Stata advice
    - We can talk through causality issues
    - Book me in advance
    - Will add an extra link near office hours with an additional scheduler
  - Lecture 14: I'll pre-record a video on structural estimation and we can chat about it
- 4. GW moving to credit/no credit upon request for courses this semester
- 5. Additional changes to office hours as already noted
- 6. Anything else?

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## Overview

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• We would like to know the effect of a policy that happens in one (or a few) regions

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• Why not diff-in-diff?



- We would like to know the effect of a policy that happens in one (or a few) regions
- Why not diff-in-diff?
  - small sample size  $\rightarrow$  big standard errors
  - · diff-in-diff requires that differences between treated and control are either
    - time-invariant, unit-specific measures or
    - time-varying in the same way for all units
- We can weaken these diff-in-diff assumptions by making a synthetic control
  - one comparison state that is a little of Michigan, a little of Illinois, no Wisconsin and a little Florida

• This doesn't fix the small sample problem, but we use different inference methods

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# Set-up



- t is time,  $t \in \{1, ..., T_0, ..., T\}$ .
- Treatment occurs after  $T_0$ .
- We look for effects starting in  $T_0 + 1$ 
  - there are  $\mathcal{T}_0$  pre-intervention periods,  $\{1,...,\mathcal{T}_0\}$
  - there are  $T_1$  post-intervention periods,  $\{T_0 + 1..., T\}$
  - total  $T = T_0 + T_1$



- *i* are observations,  $i \in \{1..., J+1\}$ , 1 is treated,  $\{2, 3, ..., J+1\}$ , or J observations, are not. We call these J observations the "donor pool"
- the donor pool should be



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- the donor pool should be
  - untreated (during observation period)
  - unaffected by treatment
  - should have no large, "idiosyncratic shocks," to the outcome variable
  - "similar" to treated units to avoid interpolation bias (though it seems like the method should do this for you)



- $Y_{it}^{I}$  outcome for treated
- $Y_{it}^N$  outcome for untreated





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- we just observe  $Y_{it}$
- we assume  $Y_{it}^{I}=Y_{it}^{N}$  for any  $t\leq T_{0}$
- $D_i = 1$  is ever treated, 0 is otherwise
- Z<sub>it</sub> are covariates
- define the effect of interest as  $\alpha_{it} = Y_{it}^I Y_{it}^N$
- what does this mean in words?



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- what does this mean in words?
- note that this effect varies with time. How does this differ from a diff-in-diff?

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## Goal of estimation

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- we want to find  $\alpha_{it} = Y_{it}^I Y_{it}^N$
- note that this is  $\alpha_{it} = Y_{it} Y_{it}^N$
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- intuition: approximate with a weighted average of non-treated units

• in math, 
$$\hat{Y}_{it}^{m{N}} = \sum_{j=2}^{J+1} w_j^* Y_{jt}$$



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Trick is to find w<sub>j</sub>

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## The Necessity of a Convex Hull



- key requirement is that  $Y_{it}^{I}$  is in the convex hull of  $Y_{it}$ ,  $i \neq j$
- what is that?
  - in general, the convex hull of X is the "smallest convex set that contains X"

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• think of a set of three points (x, y)



Note: source is http://en.wikipedia.org/wiki/File:Convex\_huld.png (E) E OQC



• think of a treated observation where the donor pool would not form a convex hull.



- think of a treated observation where the donor pool would not form a convex hull.
  - impact of elections on growth in Afghanistan. there may be no obs that are in the convex hull for Afghanistan
- a sufficient condition for having donor pool observations in the convex hull is that the "number of pre-intervention periods is large relative to the scale of the transitory shocks."

- assuming that the donor pool lies in the convex hull is equivalent to assuming  $Y_{11t} \sum_{j=2}^{J} w_j Y_{0jt} \equiv 0$  for  $t < T_0$
- the convex hull assumption is sort of testable (maybe more on this later)

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## Estimation

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• in OLS, we minimize what?





- in OLS, we minimize what?  $\sum_{j=1}^{J} \epsilon_{i}^{2}$ . In matrix language that  $\epsilon'\epsilon$
- in this case, we choose weights to minimize the difference between the treated covariates and pre-treatment outcomes and the donor pool's covariates and pre-treatment outcomes
- But remember that our optimal weights don't have a time dimension.
- here we want to choose weights  $\boldsymbol{W}$  to minimize

$$||X_1 - X_0W||$$

• X contains both covariates Z and pre-treatment outcomes Y

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		What	we are n	ninimizing		

$$X_{1} = \begin{pmatrix} Z_{11} \\ Z_{12} \\ \vdots \\ Z_{1r} \\ Y_{11} \\ Y_{12} \\ \vdots \\ Y_{1\tau_{0}} \end{pmatrix}, X_{0} = \begin{pmatrix} Z_{21} & \dots & Z_{J+1,1} \\ Z_{22} & \dots & Z_{J+1,2} \\ \vdots & \ddots & \vdots \\ Z_{2r} & \dots & Z_{J+1,r} \\ Y_{21} & \dots & Y_{J+1,1} \\ Y_{22} & \dots & Y_{J+1,2} \\ \vdots & \ddots & \vdots \\ Y_{2\tau_{0}} & \dots & Y_{J+1,\tau_{0}} \end{pmatrix}, W = \begin{pmatrix} w_{2} \\ w_{3} \\ \vdots \\ w_{J} \end{pmatrix}$$

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- Implicitly equally weights all pre-treatment obs and covariates
- You can modify this, but each choice is a judgement call
- For example, combining the pre-treatment Y into an average would down-weight them

- Note that  $||X_1 X_0W||$  doesn't give you one number it gives you  $r + T_0$  numbers.
- Final choice: how to weight those numbers when you add them up.



Suppose that there is one covariate and two observations. The matrix looks like this

$$X_{1} = \begin{pmatrix} 5\\2\\3 \end{pmatrix}, X_{0} = \begin{pmatrix} 0 & 5\\2 & 5\\3 & 8 \end{pmatrix}, W = \begin{pmatrix} w_{1}\\w_{2} \end{pmatrix}$$
$$||X_{1} - X_{0}W|| = \begin{pmatrix} 5\\2\\3 \end{pmatrix} - \begin{pmatrix} 0w_{1} + 5w_{2}\\2w_{1} + 5w_{2}\\3w_{1} + 8w_{2} \end{pmatrix} = \begin{pmatrix} 5 - (0w_{1} + 5w_{2})\\2 - (2w_{1} + 5w_{2})\\3 - (3w_{1} + 8w_{2}) \end{pmatrix}$$

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- this outcome is a vector, and we have to decide how much we care about different parts of the diversion from the treated outcome.
- That "added-up number" is the mean squared error of the estimate. That is MSE  $= ||X_1 X_0W||v$ , where v is yet another weighting matrix



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- How do you choose v? A variety of options
  - so that the pre-intervention difference in Y is minimized
  - to minimize error in the final estimation (what they do in another, similar paper)
  - cross-validation in Germany paper:
    - find W for the first half of the pre-treatment era
    - choose v such that  $||X_1 X_0W||v$  is minimized in the second half of the pre-treatment period
    - if there are multiple possible W, you can see which one gives the lowest MSPE in the second pre-treatment period



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• Note that  $||X_1 - X_0W||v$  is the Mean Squared Prediction Error: MSPE



- no effect of treatment on the untreated
- the treated unit would have had the untreated outcome in the absence of treatment

• treated observation is in the convex hull of the donor pool

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# Examples





For Germany and breastfeeding

- What unit is treated?
- What are weights?





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For Germany and breastfeeding

- What unit is treated?
- What are weights? Germany paper is clear in Table 1
- How do we interpret main outcome tables?
  - Germany: Figures 1 and 2
  - Breastfeeding: Figures 1 to 4 (vertical line in wrong place)
- Other big-picture questions?